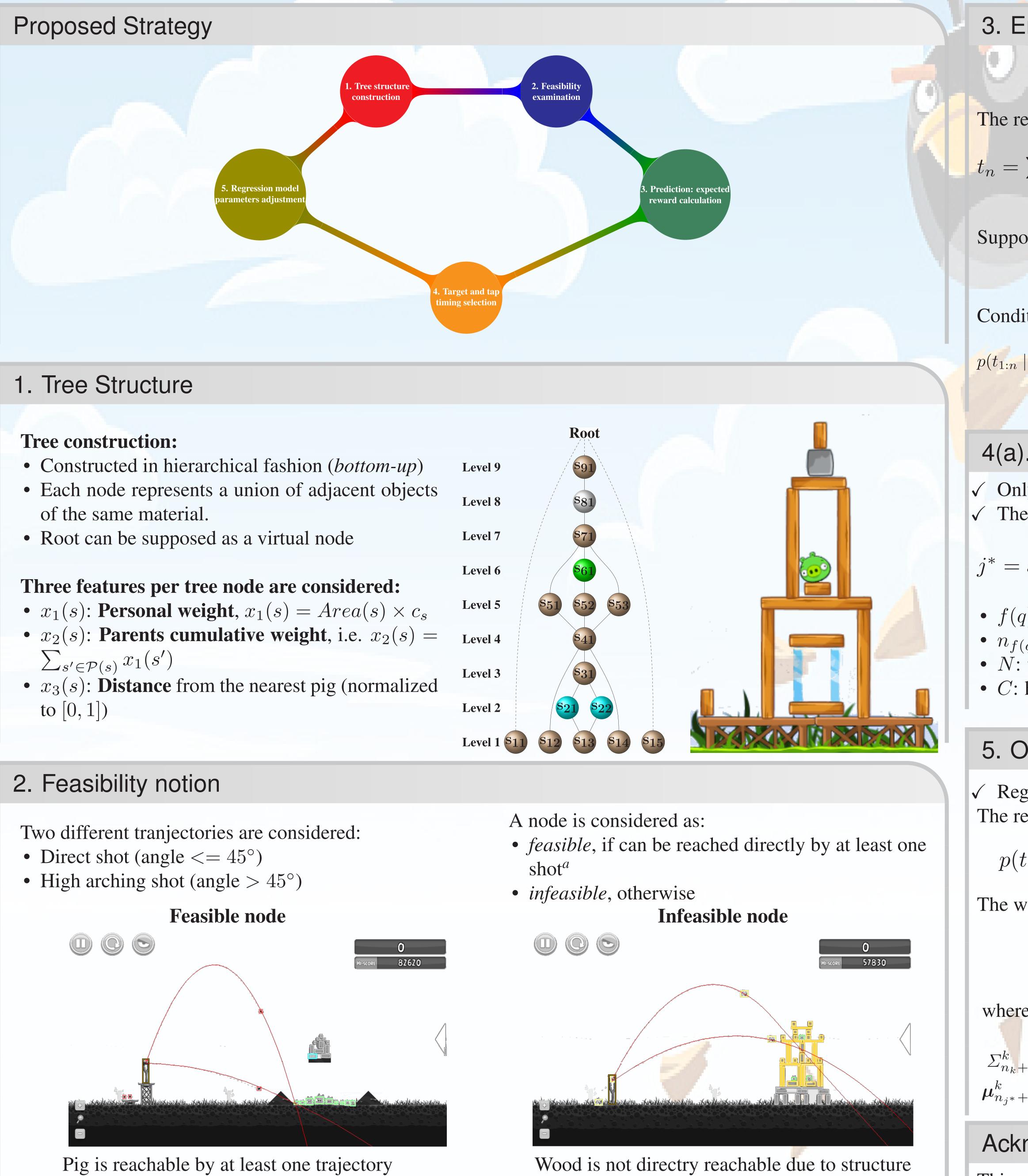
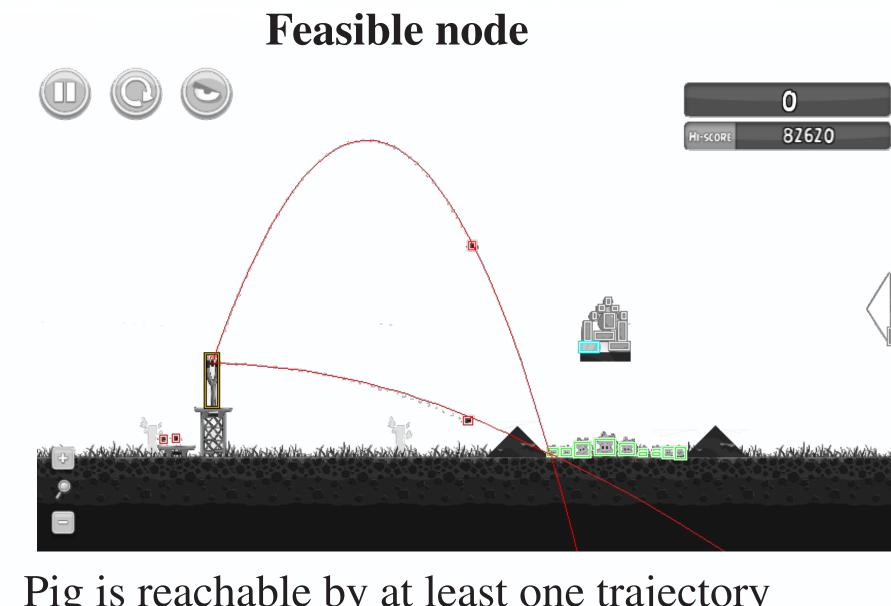


A Bayesian Ensemble Regression Framework on the Angry Birds Game Nikolaos Tziortziotis, Georgios Papagiannis and Konstantinos Blekas



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^{*a*}In the case of the white bird a node supposed as feasilbe if can be reached by bird's *egg*.

Department of Computer Science & Engineering, University of Ioannina, Greece ⊠ email: {ntziorzi, gpapagia kblekas}@cs.uoi.gr

3. Ensemble linear regresion models

A separate linear model is used for each (bird, object material) pair **Linear regression model**

The rewards are considered as the target values:

 $t_n = \sum_{i=1}^M w_i \phi_i(x_n) + \epsilon_n = \boldsymbol{w}^\top \underbrace{\boldsymbol{\phi}(\boldsymbol{x}_n)}_{\text{Gaussian kernel}} + \underbrace{\boldsymbol{\epsilon}_n}_{\text{noise}}$

Supposing that $\epsilon_n \sim \mathcal{N}(0, \beta^{-1})$,

$$t_n \mid x = x_n \sim \mathcal{N}(\boldsymbol{w}^\top \boldsymbol{\phi}(\boldsymbol{x}), \beta^{-1})$$

Conditional probability:

$$\boldsymbol{w}, \boldsymbol{\beta} = \mathcal{N}(t_{1:n} \mid \boldsymbol{\Phi} \boldsymbol{w}, \boldsymbol{\beta}^{-1}I_n), \quad t_{1:n} \triangleq \{t_k\}_{k=1}^n$$

Design matrix

4(a). Target selection mechanism

✓ Only the feasible nodes are examined \checkmark The best arm is selected greedily according to:

$$\arg\max_{q}\left\{\left(\boldsymbol{\mu}_{n_{f(q)}}^{f(q)}\right)^{\top}\boldsymbol{\phi}(\boldsymbol{x}_{q})+C\sqrt{\frac{2\ln N}{n_{f(q)}}}\right\}$$

• f(q): denotes the regression model for node, q • $n_{f(q)}$: number of times where has been selected • N: total number of plays

• C: has been selected equal to 3000

5. Online model's parameters learning

✓ Regressor $k \triangleq f(j^*)$ has been selected The received observation (reward) t_{n_k+1} follows,

$$\boldsymbol{x}_{n_k+1}|\boldsymbol{w}_k) = \mathcal{N}(t_{n_k+1}|\boldsymbol{w}_k^T\boldsymbol{\phi}(\boldsymbol{x}_{n_k+1}),\beta).$$

The weights' posterior distribution is given as:

$$p(\boldsymbol{w}_k|t_{1:n_k+1}) = p(t_{n_k+1}|\boldsymbol{w}_k)p(\boldsymbol{w}_k|t_{1:n_k})$$
$$= \mathcal{N}(\boldsymbol{w}_k|\boldsymbol{\mu}_{n_k+1}^k, \boldsymbol{\Sigma}_{n_k+1}^k),$$

where the Gaussian parameters are given as:

$$= \left[(\Sigma_{n_k}^k)^{-1} + \beta \phi(\boldsymbol{x}_{n_k+1})^T \phi(\boldsymbol{x}_{n_k+1}) \right]^{-1}$$

$$= \Sigma_{n_k+1}^k \left[\beta_k \phi^T(\boldsymbol{x}_{n_k+1}) t_{n_k+1} + (\Sigma_{n_k}^k)^{-1} \boldsymbol{\mu}_{n_k}^k \right].$$

Marginal distribution:

where,

$$\boldsymbol{\mu}_n = \beta \boldsymbol{\Sigma}_n \boldsymbol{\Phi}_n^{\mathsf{T}}$$

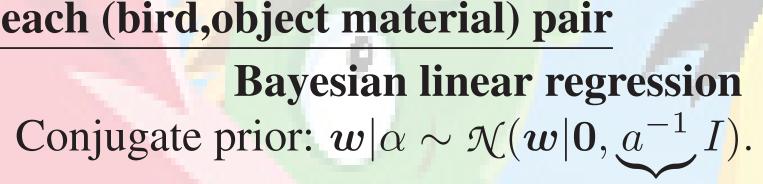
Predictive distribution:

$$p(t_*|t_{1:n}, lpha, eta)$$
 :

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 $p(\boldsymbol{w}|t_{1:n}, \alpha, \beta) = \mathcal{N}(\boldsymbol{w}|\boldsymbol{\mu}_n, \boldsymbol{\Sigma}_n),$

 $\Sigma_n^{\top} t_{1:n}$ and $\Sigma_n = (\beta \Phi_n^{\top} \Phi_n + aI)^{-1}$.

prior parameter

 $= \mathcal{N}(t_* | \boldsymbol{\mu}_n^\top \boldsymbol{\phi}(\boldsymbol{x}_*), \frac{1}{\beta} + \boldsymbol{\phi}(\boldsymbol{x}_*)^\top \boldsymbol{\Sigma}_n \boldsymbol{\phi}(\boldsymbol{x}_*)).$

4(b). Tapping selection

No tapping

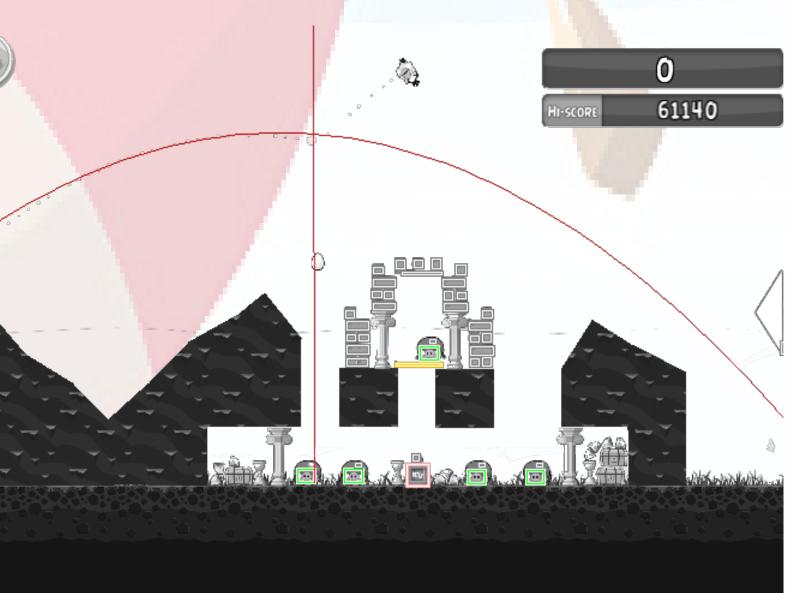
At the 75% of the trajectory from the slingshot to the first collision point

At the 85% of the trajectory(direct shot) At the 90% of the trajectory(high-arching)

The tapping is performed when the bird lie above the target

No tapping

White bird tapping



A node supposed as feasible if can be reached by bird's *egg*.